

VII. FOURIER ANALYSIS OF SAMPLE FUNCTIONS OF
STATIONARY PROCESSES

1. Generalization of Fourier Transforms.

(a) Formal Definitions.

Fourier Transform; $f(t) = \mathcal{F}g(t) = \int e^{i\lambda t} g(\lambda) d\lambda$

Inverse Fourier transform; $g(\lambda) = \mathcal{F}^{-1}f(\lambda) = \frac{1}{2\pi} \int e^{-i\lambda t} f(t) dt$

(b) $g \in L^2 \rightleftharpoons f \in L^2$

$$f(t) = \mathcal{F}g(t) = \text{l.i.m.}_{A \rightarrow \infty} \int_{-A}^A e^{i\lambda t} g(\lambda) d\lambda$$

$$\Updownarrow$$

$$g(\lambda) = \mathcal{F}^{-1}f(\lambda) = \text{l.i.m.}_{A \rightarrow \infty} \frac{1}{2\pi} \int_{-A}^A e^{-i\lambda t} f(t) dt$$

(c) $g \in L^2 \rightleftharpoons f$ continuous, vanishing at $\pm \infty$

$$f(t) = \mathcal{F}g(t) = \int_{-\infty}^{\infty} e^{i\lambda t} g(\lambda) d\lambda \quad (\text{Lebesgue integral})$$

$$\Downarrow$$

$$g(\lambda) = \mathcal{F}^{-1}f(\lambda) = \text{a.e.} \lim_{\epsilon \rightarrow 0} \lim_{A \rightarrow \infty} \frac{1}{2\pi} \int_{-A}^A e^{-i\lambda t} \frac{e^{-it\epsilon} - 1}{-it\epsilon} f(t) dt$$

(d) dG complex measure of bounded variation

$\vec{f} = \mathcal{J}dG$ continuous, bounded

$$\mathcal{J}(dG)(t) = \int_{-\infty}^{\infty} e^{i\lambda t} dG(\lambda) \quad (\text{Stieltjes integral})$$

$$G(b) - G(a) = \lim_{A \rightarrow \infty} \frac{1}{2\pi} \int_{-A}^A \int_a^b e^{-it\lambda} d\lambda f(t) dt \quad (\text{P. Lévy's formula})$$

$$G(x) = \frac{G(x+0) + G(x-0)}{2}$$

Special Case. dG purely discontinuous

$\vec{f} = \mathcal{J}dG$ almost periodic function in Bohr's sense

(e) S. Bochner: integrated Fourier transform

(f) L. Schwartz: Fourier transform of slowly increasing distributions.

2. Fourier Transform of Slowly Increasing Distributions.

(a) Space \mathcal{S} : $f \in \mathcal{S} \iff f \in C^\infty$ and $|x^m f^{(n)}(x)|$ bounded for each (m, n)
def

$$\|f\| = \sum_{m,n} 2^{-(m+n)} \frac{\|f\|_{m,n}}{1 + \|f\|_{m,n}}$$

$$\|f\|_{m,n} = \sup_x |x^m f^{(n)}(x)|$$

$$\|f_p\| \rightarrow 0 \quad (p \rightarrow \infty)$$

$$\vec{x}^m f_p^{(n)}(x) \rightarrow 0 \quad \text{uniformly in } x \quad (p \rightarrow \infty)$$

$f \in \mathcal{S}$ is called a rapidly decreasing function.

\mathcal{S} is a linear topological space (in fact a Frechet space) invariant under derivation and Fourier transform.

(b) Space \mathcal{S}' : \mathcal{S}' is the dual space of \mathcal{S} , i.e.,

$u \in \mathcal{S}' \stackrel{\text{def}}{\iff} u$ is a continuous linear functional defined on \mathcal{S}

$\langle u, \varphi \rangle =$ the value of $u(\varepsilon \mathcal{S})$ at $\varphi(\varepsilon \mathcal{S})$.

$u \in \mathcal{S}'$ is called a slowly increasing distribution.

\mathcal{S}' is a topological space invariant under derivation and Fourier transform

(i) topology in \mathcal{S}' . pseudo-topology $u_n \rightarrow 0 \iff \langle u_n, \varphi \rangle \rightarrow 0$ for all φ .

(ii) derivation in \mathcal{S}' $\langle Du, \varphi \rangle \stackrel{\text{def}}{=} - \langle u, \varphi' \rangle$

(iii) Fourier transforms in \mathcal{S}'

$$\langle \mathcal{F}u, \varphi \rangle \stackrel{\text{def}}{=} \langle u, \mathcal{F}\varphi \rangle$$

$$\langle \overline{\mathcal{F}}u, \varphi \rangle \stackrel{\text{def}}{=} \langle u, \mathcal{F}\varphi \rangle$$

It is easy to see $\overline{\mathcal{F}} = \mathcal{F}^{-1}$, $\mathcal{F} = \overline{\mathcal{F}}^{-1}$

Example 1. A function g is called a slowly increasing function if

$$\int_{-\infty}^{\infty} \frac{|g(\lambda)|}{1 + |\lambda|^p} d\lambda < \infty \quad \text{for some } p > 0$$

Such function g is a slowly increasing distribution in the sense

$$\langle g, \varphi \rangle = \int_{-\infty}^{\infty} g(\lambda) \varphi(\lambda) d\lambda$$

It is easy to see

$$\mathcal{F}g = \lim_{A \rightarrow \infty} (\text{in } \mathcal{S}') \int_{-A}^A e^{it\lambda} g(\lambda) d\lambda$$

Example 2. A locally bounded variation complex measure dG is called a slowly increasing measure if

$$\int_{-\infty}^{\infty} \frac{|dG(\lambda)|}{1 + |\lambda|^p} d\lambda < \infty \quad \text{for some } p > 0$$

Such measure is a slowly increasing distribution in the sense

$$\langle dG, \varphi \rangle = \int_{-\infty}^{\infty} \varphi(\lambda) dG(\lambda)$$

It is easy to see

$$\mathcal{F}dG = \lim_{A \rightarrow \infty} (\text{in } \mathcal{H}) \int_{-A}^A e^{it\lambda} dG(\lambda)$$

Example 3.

$$f \in L^p \quad (1 \leq p \leq \infty)$$

$\Rightarrow f$ is a slowly increasing function

Example 4. δ is clearly a slowly increasing measure and

$$\mathcal{F}\delta = 1, \quad \overline{\mathcal{F}\delta} = \frac{1}{2\pi}$$

$$\mathcal{F}1 = \overline{\mathcal{F}}^{-1} 1 = 2\pi\delta$$

$$\overline{\mathcal{F}}1 = \mathcal{F}^{-1} 1 = \delta$$

Example 5.

$$\begin{aligned} \langle \mathcal{F}D\delta, \varphi \rangle &= \langle D\delta, \mathcal{F}\varphi \rangle \\ &= \langle \delta, D\mathcal{F}\varphi \rangle \\ &= D\mathcal{F}\varphi(0) \\ &= \frac{d}{d\lambda} \int_{-\infty}^{\infty} e^{i\lambda t} \varphi(t) dt \Big|_{\lambda=0} \\ &= \int_{-\infty}^{\infty} e^{i\lambda t} i t \varphi(t) dt \Big|_{\lambda=0} \\ &= \int_{-\infty}^{\infty} i t \varphi(t) dt \end{aligned}$$

$$\therefore \mathcal{F}(D\delta) = it$$

Example 6. If dG is a slowly increasing measure, then $G(\lambda)$ is a slowly increasing function and

$$DG = dG.$$

3. Spectral Decomposition of the Sample Functions of Weakly Stationary Processes.

(a) Let $x(t) = x(t, \omega)$ be a weakly stationary process with

$$(1) \quad (x(t), 1) = 0$$

and

$$(2) \quad r(t) = (x(t+s), x(s))$$

is continuous.

Then we have

$$(3) \quad \text{Hincin decomposition: } r(t) = \int e^{it\lambda} dF(\lambda)$$

$$(4) \quad \text{Kolmogorov-Cramer decomposition: } x(t) = \int e^{it\lambda} dM(\lambda)$$

(b) Regularization of $x(t)$.

Theorem 1. Given a weakly stationary process with (1) and (2), there exists a function $f(t, \omega)$ Borel measurable in (t, ω) such that, for each t ,

$$(5) \quad f(t, \omega) = x(t, \omega) \quad \text{for a.a. } \omega$$

Such $f(t, \omega)$ is uniquely determined up to $dt \cdot dP(\omega)$ -measure 0 and is called the regularization of $x(t)$.

Theorem 2. The regularization $f(t, \omega)$ in Theorem 1 is a slowly increasing function of t for a.a. ω . In fact

$$(6) \quad \int_{-\infty}^{\infty} \frac{|f(t, \omega)|}{1+t^2} dt < \infty, \quad \text{for a.a. } \omega$$

(c) Regularization of $M(\lambda)$. Let $M(\lambda)$ denote $M(-\infty, \lambda]$. Then $M(\lambda)$ is right continuous in the $L^2(\Omega)$ -norm and has orthogonal increments.

Theorem 3. There exists a function $G(\lambda, \omega)$ Borel measurable in (λ, ω) such that, for each λ ,

$$(6) \quad G(\lambda, \omega) = M(\lambda, \omega), \quad \text{for a.a. } \omega$$

Such G is uniquely determined up to $d\lambda \cdot dP(\omega)$ -measure 0 and is called the regularization of $M(\lambda, \omega)$

Theorem 4. The regularization $G(\lambda, \omega)$ is a slowly increasing function of λ for a.a. ω and so $D_\lambda G \in \mathcal{J}'$ for a.a. ω . In fact

$$\int \frac{|G(\lambda, \omega)|}{1+\lambda^2} d\lambda < \infty \quad \text{for a.a. } \omega$$

(d) Spectral Decomposition. Let $x(t)$ be a weakly stationary process with the Kolmogorov-Cramer decomposition

$$x(t) = \int e^{i\lambda t} dM(\lambda)$$

and $f(t, \omega)$ and $G(\lambda, \omega)$ be the regularizations of $x(t)$ and $M(\lambda)$ respectively.

Theorem 5. $f = \mathcal{F}[DG]$ for a.a. ω where \mathcal{F} is the Fourier transform in \mathcal{S}' .

(e) Examples. We use the same notations as before. By taking Doob's separable version if necessary, we can assume that $f(t, \omega)$ and $G(\lambda, \omega)$ are r_A separable and measurable.

Ex.1. If $r(t) = \sum_n a_n e^{i\lambda_n t}$ with $\sum_n \sqrt{a_n} < \infty$, then

$$f(t, \omega) = \sum_n M_n(\omega) e^{i\lambda_n t},$$

where $M_n = M(\lambda_n^+ 0) - M(\lambda_n^- 0)$, $\sum_n |M_n| < \infty$ d.e.

$$G(\lambda, \omega) = \sum_{\lambda_n < \lambda} M_n$$
 bounded variation on $(-\infty, \infty)$.

Ex.2. If $x(t)$ is Gaussian and $F(\lambda)$ is continuous and strictly increasing, then

$f(t, \omega)$ is unbounded in $-\infty < t < \infty$ for a.a. ω .

$G(\lambda, \omega)$ is continuous in $-\infty < \lambda < \infty$ but not of bounded variation on any small λ -interval for a.a. ω .

Ex.3. If $x(t)$ is Gaussian, then $G(\lambda, \omega)$ has only the first kind discontinuities in λ for a.a. ω .

Ex.4. (Yu. K. Belajev) If $r(t)$ is analytic in $-\infty < t < \infty$ (for example if $\int_{-\infty}^{\infty} e^{c|\lambda|} dF(\lambda) < \infty$ for every $c > 0$, in particular if the support of dF is compact), then $f(t, \omega)$ is analytic in $-\infty < t < \infty$ for a.a. ω .

Ex.5. There exists a strictly stationary process whose sample paths (regularization) are unbounded on every interval. For example, take a periodic function $g(t)$ with period 1 which is square summable on $[0, 1]$ and unbounded on every interval; the existence of such g is easily seen. Now set

$$x(t, \omega) = g(t + \omega), \quad \omega \in \Omega \equiv [0, 1].$$

Then $x(t, \omega)$ satisfies our conditions.

4. Generalized Harmonic Analysis of Sample Functions of Strictly Stationary Processes.

Definition 1. A complex valued function $f(t)$ of a real variable $t = (-\infty, \infty)$ is said to belong to the Wiener class (or Wiener-Hopf class) \mathcal{N} if

(1) $f(t)$ is measurable

(2) $R(t) \equiv R(t : f) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T f(t+s) \overline{f(s)} ds$ is convergent for

a.a. t including $t = 0$.

(3) $\lim_{\epsilon \downarrow 0} \frac{1}{2\epsilon} \int_{-\epsilon}^{\epsilon} R(t) dt = R(0)$

Remark 1. Wiener required the existence of $R(t)$ at every point t and its continuity. Hopf defined $R(t)$ by

$$(2') \quad \lim_{\substack{A \rightarrow -\infty \\ B \rightarrow \infty}} \frac{1}{B-A} \int_A^B f(t+s) \overline{f(s)} ds$$

instead of (2).

Remark 2. We can deduce the following properties from (1) and (2) without using (3)

$$(4) \quad |R(t)| \leq R(0) \quad \text{a.e.}$$

$$(5) \frac{1}{2\epsilon} \int_{-\epsilon}^{\epsilon} R(t) dt \text{ is real and } \leq R(0)$$

(6) $R(t)$ is a measurable positive definite function in the sense that $\int \int R(t-s) \varphi(t) \overline{\varphi(s)} dt ds \geq 0$ for every continuous function φ with compact support and so it has Bochner's representation

$$R(t) = \int_{-\infty}^{\infty} e^{i\lambda t} d\mathbb{Y}(\lambda) \quad \text{for a.a.t.}$$

where $d\mathbb{Y}$ is a bounded measure on $(-\infty, \infty)$.

Thus the limit of the left side in (3) exists and is $\leq R(0)$.

The condition (3) claims that the equality holds.

Remark 3. (3) does not follow from (1) and (2). See the example $f(t) = \sin(t^2)$. Then $R(t) \equiv 0$ for $t \neq 0$ and $R(0) = 1/2$.

Definition 2. $R(t)$ is called the auto-correlation function of $f(t)$ and $d\mathbb{Y}$ is called the spectral measure of f .

Example 1. $f(t) = \sum a_n e^{i\lambda_n t}$
 $\Rightarrow f \in \mathcal{N}$ and $R(t) = \sum |a_n|^2 e^{i\lambda_n t}$

Example 2. $f(t) = \int e^{i\lambda t} dG(\lambda) \quad \int |dG(\lambda)| < \infty$
 $\Rightarrow f \in \mathcal{N}$ and $R(t) = \int e^{i\lambda t} |dG(\lambda)|^2$

where $\{\lambda_n\}$ are points of discontinuity of G and c_n is the jump at a_n for each n .

In these examples the spectral measures are purely discontinuous. See Theorem 4 for the existence of a function $\epsilon \mathcal{N}$ with given general spectral measure.

Theorem 1. If $f \in \mathcal{N}$, then

$$(7) \quad \int_{-\infty}^{\infty} \frac{|f(t)|^2}{1+t^2} dt < \infty$$

and f is therefore a slowly increasing function.

Proof. Set $S_n = \frac{1}{n} \int_{-n}^n |f(s)|^2 ds$. Then S_n is convergent by (2) and

so bounded

$$\begin{aligned} \int_{-N}^N \frac{|f(t)|^2}{1+t^2} dt &= \sum_{n=0}^{N-1} \int_{n \leq |t| < n+1} \frac{|f(t)|^2}{1+t^2} dt \\ &\leq \sum_{n=0}^{N-1} \frac{1}{1+n^2} \left[(n+1) S_{n+1} - n S_n \right] \quad (S_0 = 0) \\ &= \sum_{n=1}^N \left[\frac{1}{1+(n-1)^2} - \frac{1}{1+n^2} \right] n S_n \\ &= \sum_{n=1}^N O(1/n^2) \end{aligned}$$

which implies (7). f is then a slowly increasing function by virtue of Schwarz inequality.

By Theorem 1 we can express f as the Fourier transform of a distribution $\epsilon \mathcal{S}'$, but we have a more concrete expression.

Theorem 2. (N. Wiener). If $f \in \mathcal{N}$, then

$$(8) \quad g(\lambda) = \frac{1}{2\pi} \int_{-1}^1 f(t) \frac{e^{-i\lambda t} - 1}{-it} dt$$

$$+ \text{l.i.m.}_{A \rightarrow \infty} \frac{1}{2\pi} \left[\int_1^A + \int_{-A}^{-1} \right] f(t) \frac{e^{-i\lambda t}}{-it} dt$$

is well defined and we have

$$(9) \quad f(t) = \lim_{\epsilon \downarrow 0} \text{l.i.m.}_{A \rightarrow \infty} \int_{-A}^A e^{i\lambda t} \frac{g(\lambda + \epsilon) - g(\lambda - \epsilon)}{2\epsilon} d\lambda$$

$$(10) \quad R(t : f) = \lim_{\epsilon \downarrow 0} \int_{-\infty}^{\infty} e^{i\lambda t} \frac{|g(\lambda + \epsilon) - g(\lambda - \epsilon)|^2}{2\epsilon} d\lambda$$

and

$$(11) \quad d\Psi(t : f) = \lim_{\epsilon \downarrow 0} \frac{|g(\lambda + \epsilon) - g(\lambda - \epsilon)|^2}{2\epsilon} d\lambda.$$

Theorem 3. Let $x(t)$ be a strictly stationary process with mean 0 and continuous covariance function $r(t) (= \int e^{i\lambda t} dF(\lambda))$. Then the regularization $f(t, w)$ of $x(t)$ (as a function of t) belongs to \mathcal{N} for a.a.w.

Furthermore, if $x(t, \omega)$ is ergodic, then

$$(12) \quad R(t; f(\cdot, \omega)) = \overline{f(t)} \quad \text{for a.a.w.}$$

and so

$$(13) \quad d\mathbb{P}(\cdot; f(\cdot, \omega)) = d\mathbb{P}(\lambda) \quad \text{for a.a.w.}$$

Proof. Consider $y(\omega) = f(t, \omega) \overline{f(0, \omega)}$ for any fixed t . Then y is $\mathcal{B}(x)$ -measurable, $y \in L^1(\Omega, \mathcal{B}(x), P)$ and

$$\phi_s y(\omega) = f(t+s, \omega) \overline{f(s, \omega)}$$

(see page IV 5.6 for the shift operator ϕ_s). The individual ergodic theorem shows that

$$R(t, \omega) \equiv R(t; f(\cdot, \omega)) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T f(t+s, \omega) \overline{f(s, \omega)} ds$$

exists for a.a.w., belongs to $L^1(\Omega, \mathcal{B}(x), P)$, is invariant under the shift ϕ_s and

$$E[R(t, \omega)] = E(y) = \overline{f(t)}$$

Since $f(t, w)$ is Borel measurable in (t, w) , we can use Fubini's theorem to conclude that, for a.a.w. $R(t, w)$ is determined for a.a.t. Since $R(0, w)$ is determined for a.a.w, we can say that, for $w \in \Omega_1$, $P(\Omega_1) = 1$, $R(t, w)$ is determined for a.a.t including $t = 0$. By the remark mentioned above, $|R(t, w)| \leq |R(0, w)|$,

$$\tilde{R}(w) = \lim_{\epsilon \downarrow 0} \frac{1}{2\epsilon} \int_{-\epsilon}^{\epsilon} R(t, w) dt$$

exists and is real and $\leq R(0, w)$ for $w \in \Omega_1$. But

$$\begin{aligned} E[R(0, w) - \tilde{R}(w)] &= r(0) - E[\tilde{R}(w)] \\ &= r(0) - \lim_{\epsilon \downarrow 0} \frac{1}{2\epsilon} \int_{-\epsilon}^{\epsilon} E[R(t, w)] dt \\ &= r(0) - \lim_{\epsilon \downarrow 0} \frac{1}{2\epsilon} \int_{-\epsilon}^{\epsilon} r(t) dt = 0 \end{aligned}$$

Therefore $\tilde{R} = R(0, w)$ for $w \in \Omega_2$, $P(\Omega_2) = 1$. Thus (1), (2), (3) hold for $f(t, w)$ if $w \in \Omega_1 \cap \Omega_2$, which proves the first half of our theorem.

To prove the second half, notice that $R(t, w)$ is invariant under shifts and so independent of w .

Remark 2. If we apply Theorem 2 to $f(t, w)$ in Theorem 2, we can get

$$f(t, w) = \lim_{\epsilon \downarrow 0} \lim_{A \rightarrow \infty} \text{l.i.m.} \int_{-A}^A e^{it\lambda} \frac{g(\lambda + \epsilon) - g(\lambda - \epsilon)}{2\epsilon} d\lambda \quad \text{for a.a.w}$$

(Notice l.i.m. means limit in the $L^2((-\infty, \infty), dt)$ norm) and this is a concrete version of $f = \mathcal{F}(DG)$ established on page VIII.8 (Theorem 5); It is easy to see that $g(\lambda, w) - G(\lambda, w)$ is a constant (depending only on w) for a.a.w.

Theorem 4. Given any bounded measure dF there exists at least one function whose spectral measure is dF .

Proof. In page III.25 (Theorem 5) we proved the existence of an ergodic strictly stationary process with the covariance function $r(t) = \int e^{i\lambda t} dF(\lambda)$. Then the second part of Theorem 3 proved above shows that almost all sample functions (regularization) has the auto-correlation function $r(t)$ and so the spectral measure dF .